

A → down
B → program steps
C → up

1. → **Set the decimal point**
1 x B:

d	P		
---	---	--	--

→ C/A up or down
2. **Set the lower end of the range**
2 x B:

A	n		4
---	---	--	---

→ C/A up or down
3. **Set the upper end of the range**
3 x B:

A	n	2	0
---	---	---	---

C/A up or down

4. **To enable error codes**
3 x B:

L	1		
---	---	--	--

1 x C:

			1
--	--	--	---

 on
→ 1 x A:

			0
--	--	--	---

 off
C/A up or down
Errors are shown as F1 for an underrange condition, and F2 for an overrange condition

5. **Set digital filtering value**
5 x B:

F	I	L	T
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1 x C:

			0
--	--	--	---

 0.2 seconds
2 x C:

			1
--	--	--	---

 0.5 seconds
3 x C:

			2
--	--	--	---

 1.0 seconds
→ 4 x C:

			3
--	--	--	---

 1.5 seconds
C/A up or down
6. **Return to measurement mode**
2 x A